Low-Degree Hardness of Random Optimization Problems

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Joint work with:



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Aukosh Jagannath _{Waterloo}

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Q: In cases where it seems hard to reach a particular objective value, can we understand why? In a $\underline{unified}$ way?

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Local algorithms achieve value ALG <u>and no better</u> [Gamarnik, Sudan '13; Rahman, Virág '14]

Example (spherical *p*-spin model): for $Y \in \mathbb{R}^{\otimes p}$ i.i.d. $\mathcal{N}(0, 1)$,

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Approximate message passing (AMP) algorithms achieve value ALG <u>and no better</u> [El Alaoui, Montanari, Sellke '20]

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<u>Solution</u>: lower bounds against a larger class of algorithms (low-degree polynomials) that contains both local and AMP algorithms

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Examples of low-degree algorithms: input $Y \in \mathbb{R}^{n \times n}$

- Power iteration: Y^k1
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- Local algorithms on sparse graphs
- Or any of the above applied to $\tilde{Y} = g(Y)$

Planted Problems

For problems with a planted signal, the low-degree framework is already well-established

[Barak, Hopkins, Kelner, Kothari, Moitra, Potechin '16] [Hopkins, Steurer '17] [Hopkins, Kothari, Potechin, Raghavendra, Schramm, Steurer '17] [Hopkins '18] (PhD thesis)

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Example (planted clique): G(n, 1/2) with planted k-clique





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"Robustness": Gaussian elimination for XOR-SAT

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- Objective: $H(f(Y)) \ge \mathsf{OPT} \epsilon$
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Result: no low-degree polynomial can achieve $(1 + \frac{1}{\sqrt{2}})\frac{\log d}{d}n$

10/18

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$$f_i(Y) \in [0, 1/3] \cup [2/3, 1]$$
 for most *i*

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Forthcoming: improve $1 + \frac{1}{\sqrt{2}} \rightarrow 1 + \epsilon$ (optimal)

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For random optimization problems, need different approach:

- Stability of low-degree polynomials
- Overlap gap property (OGP)

[Gamarnik, Sudan '13] [Chen, Gamarnik, Panchenko, Rahman '17] [Gamarnik, Jagannath '19]

Theorem

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Low-Degree Polynomials are Stable

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Proof: low-degree polynomials have

- Low noise sensitivty
- Low total influence
- Hypercontractivity



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With non-trivial probability (over path), f's output is "smooth"

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Proof: first moment method [Gamarnik, Sudan '13]

Ensemble OGP

Ensemble OGP: with high probability, $\forall i, j$ on the interpolation path

 $Y^{(0)}$ $Y^{(1)}$ $Y^{(2)}$ \cdots $Y^{(m-1)}$ $Y^{(m)}$

there is no occurrence of

- S independent set in $Y^{(i)}$
- T independent set in $Y^{(j)}$

$$|S|, |T| \approx (1 + \frac{1}{\sqrt{2}})\Phi$$

 $\blacktriangleright |S \cap T| \approx \Phi$

Proof that low-degree polynomials fail:

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 $\begin{array}{l} \underline{\text{Separation}}: \ f(Y^{(0)}) \ \text{and} \ f(Y^{(m)}) \ \text{are "far apart"} \\ \underline{\text{Stability}}: \ \text{with probability} \gtrsim n^{-D}, \ \text{there are no big "jumps"} \\ f(Y^{(i)}) \rightarrow f(Y^{(i+1)}) \end{array} \end{array}$

Contradicts OGP

• Improvement to $(1+\epsilon)\frac{\log d}{d}n$

▶ Inspired by [Rahman, Virág '14]

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Langevin dynamics

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Langevin dynamics

Connections between heuristics

▶ OGP → Low-Degree

References for the Low-Degree Framework

Detection (survey article)

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Recovery

Computational Barriers to Estimation from Low-Degree Polynomials

Schramm, W.

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Optimization

Low-Degree Hardness of Random Optimization Problems Gamarnik, Jagannath, W. *arXiv:2004.12063*