

Low-Degree Hardness of Random Optimization Problems

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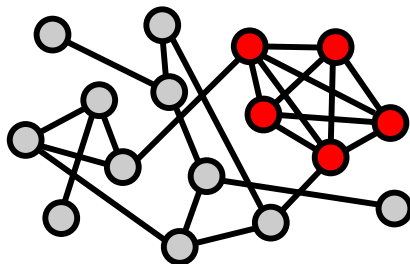
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Q: What is the typical value of the optimum (OPT)?

Q: What objective value can be reached algorithmically (ALG)?

Q: In cases where it seems hard to reach a particular objective value, can we understand why? In a unified way?

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Example (max independent set): given sparse graph $G(n, d/n)$,

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Local algorithms achieve value ALG **and no better**

[Gamarnik, Sudan '13; Rahman, Virág '14]

Spherical Spin Glass

Example (spherical p -spin model): for $Y \in (\mathbb{R}^n)^{\otimes p}$ i.i.d. $\mathcal{N}(0, 1)$,

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$\text{ALG}_p < \text{OPT}_p$ (for $p \geq 3$)

Approximate message passing (AMP) algorithms achieve value ALG_p and no better [El Alaoui, Montanari, Sellke '20]

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Solution: lower bounds against a larger class of algorithms (**low-degree polynomials**) that contains both local and AMP algorithms

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- ▶ Power iteration: $Y^k \mathbf{1}$
- ▶ Approximate message passing
- ▶ Local algorithms on sparse graphs
- ▶ Or any of the above applied to $\tilde{Y} = g(Y)$

Planted Problems

Low-degree algorithms are already well-studied for problems with a **planted signal**

[Barak, Hopkins, Kelner, Kothari, Moitra, Potechin '16]

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This work: extend low-degree framework to non-planted setting

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For some $\epsilon > 0$, no $f : (\mathbb{R}^n)^{\otimes p} \rightarrow \mathbb{R}$ of degree $\text{polylog}(n)$
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- ▶ $\{i : f_i(Y) \in [2/3, 1]\}$ is a near-indep set of size $(1 + \epsilon) \frac{\log d}{d} n$

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For random optimization problems, need different approach:

- ▶ Stability of low-degree polynomials
- ▶ Overlap gap property (OGP)
 - [Gamarnik, Sudan '13]
 - [Rahman, Virág '14]
 - [Chen, Gamarnik, Panchenko, Rahman '17]
 - [Gamarnik, Jagannath '19]

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With non-trivial probability (over path), f 's output is “smooth”

Overlap Gap Property [Gamarnik, Sudan '13]

Overlap gap property (OGP): with high probability over $Y \sim G(n, d/n)$, there does not exist $S, T \subseteq [n]$ such that

- ▶ S, T independent sets
- ▶ $|S|, |T| \geq (1 + \frac{1}{\sqrt{2}})\Phi \quad \Phi := \frac{\log d}{d}n$
- ▶ $|S \cap T| \approx \Phi$

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Proof: first moment method [Gamarnik, Sudan '13]

Ensemble OGP [CGPR'17, GJ'19]

Ensemble OGP: with high probability over

$$Y^{(0)} \quad Y^{(1)} \quad Y^{(2)} \quad \dots \quad Y^{(m-1)} \quad Y^{(m)}$$

there does not exist $S, T \subseteq [n]$ such that

- ▶ S independent set in some $Y^{(i)}$
- ▶ T independent set in some $Y^{(j)}$
- ▶ $|S|, |T| \geq (1 + \frac{1}{\sqrt{2}})\Phi \quad \Phi := \frac{\log d}{d}n$
- ▶ $|S \cap T| \approx \Phi$

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Contradicts OGP

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Forbidden structure: with high probability over

$$Y^{(0)} \quad Y^{(1)} \quad \dots \quad Y^{(Lm)} \quad (L \approx 1/\epsilon^2)$$

there does not exist $S_0, \dots, S_L \subseteq [n]$ such that

- ▶ S_k independent set in some $Y^{(t_k)}$
- ▶ $|S_k| \geq (1 + \epsilon)\Phi$
- ▶ $|S_k \setminus (\cup_{i < k} S_i)| \in [\frac{\epsilon}{4}\Phi, \frac{\epsilon}{2}\Phi]$

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 - ▶ After m steps, algorithm's output must change

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- ▶ Langevin dynamics
- ▶ Connections between heuristics
 - ▶ OGP \rightarrow Low-Degree

References for the Low-Degree Framework

- ▶ **Detection (survey article)**
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